

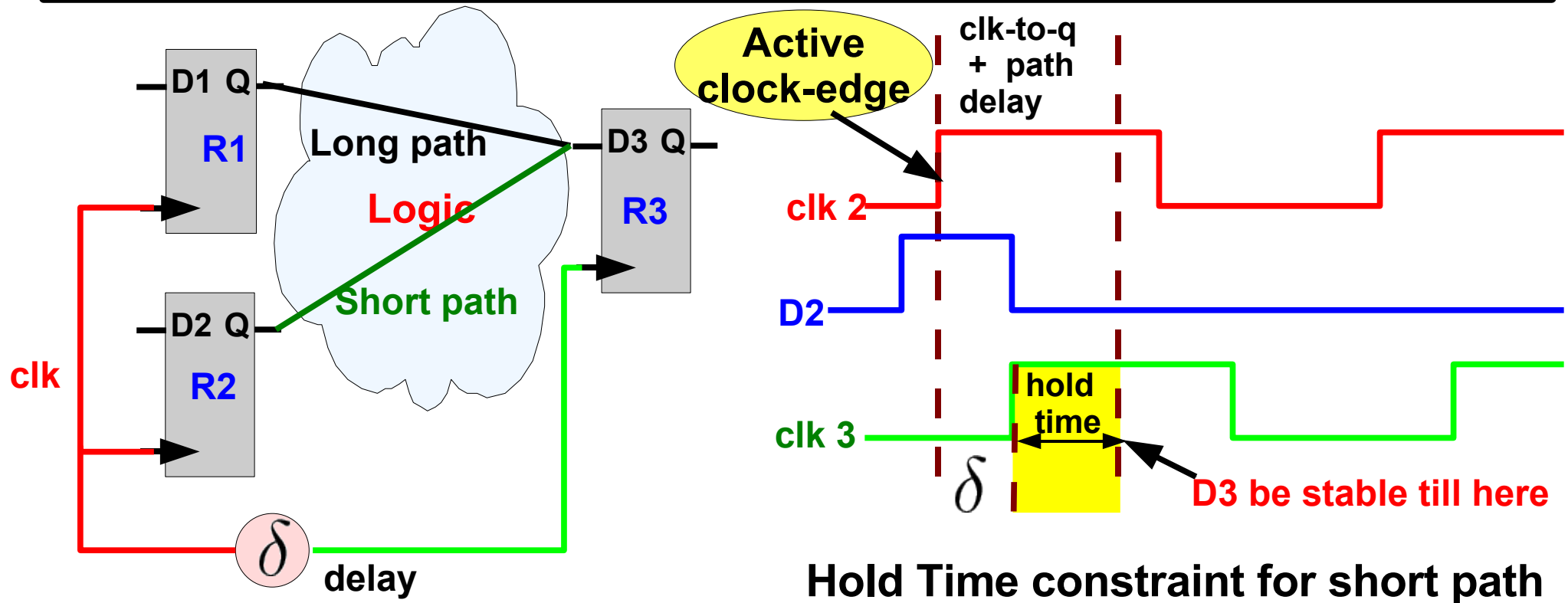
Interdependent Latch Setup/Hold Time Characterization via Euler- Newton Curve Tracing on State- Transition Equations

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Setup/Hold Times in Timing Analysis



$$\text{hold-time}_{R3} + \delta < \text{clk-to-Q-delay}_{R2} + \text{short-path-delay}$$

$$T > \text{clock-to-delay}_{R1} + \text{long-path-delay} + \text{setup-time}_{R3} - \delta$$

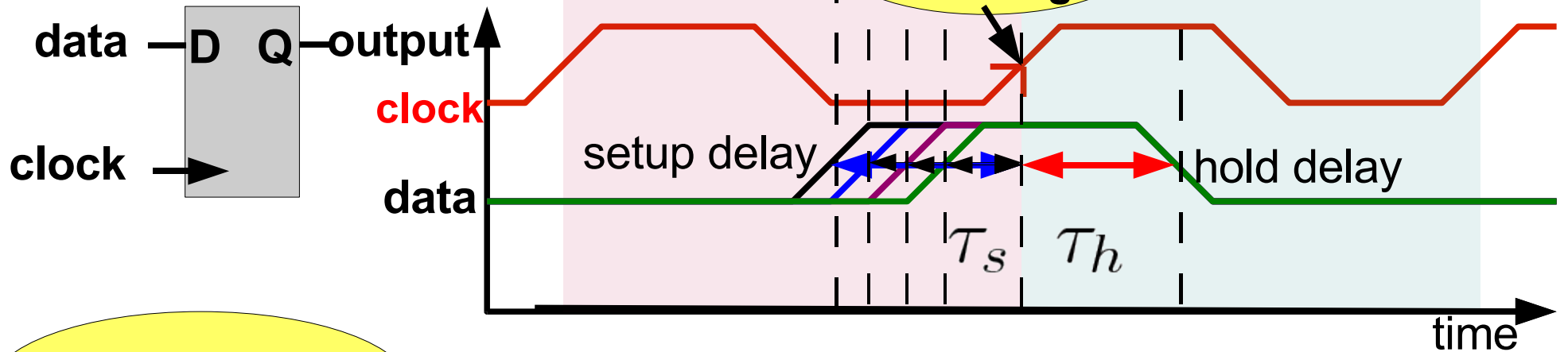
Setup/Hold Times: Important and Expensive

■ Finding setup/hold times

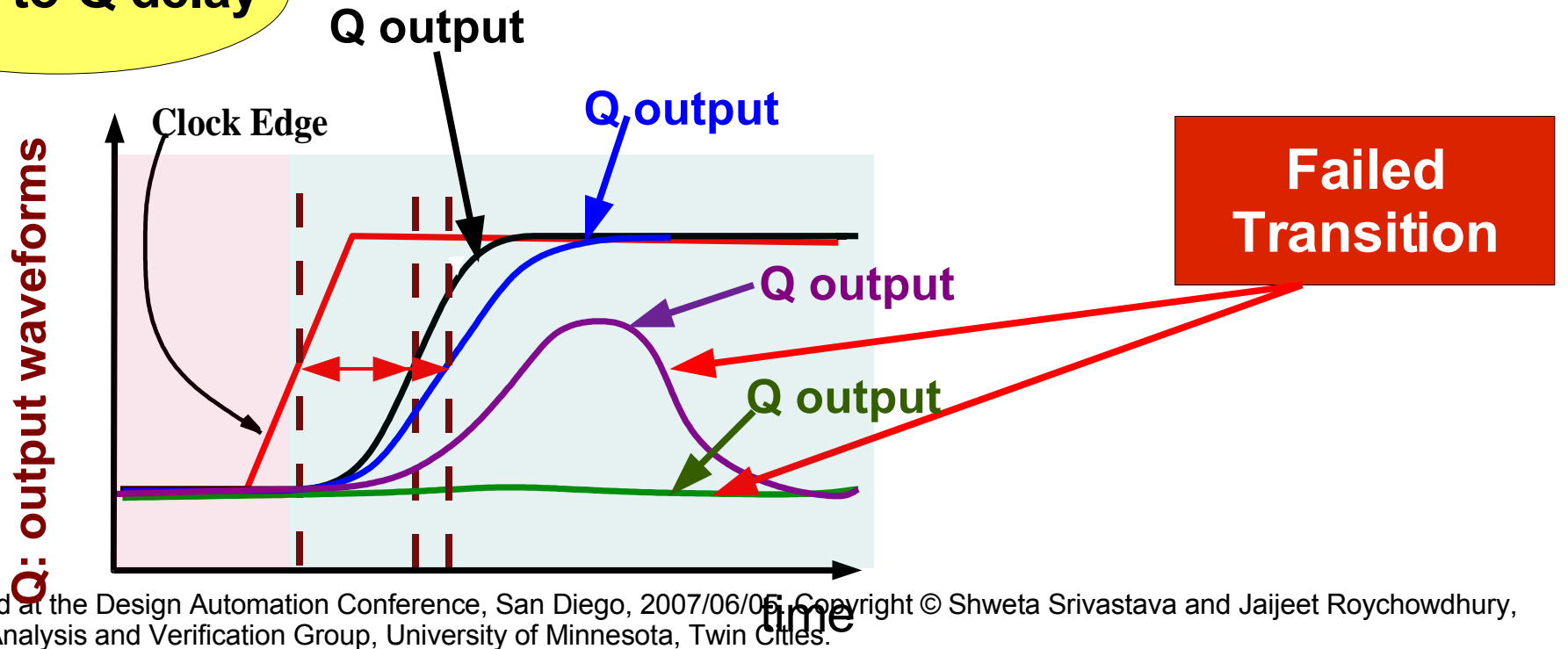
- ★ Crucial component of library characterization
- ★ **Accuracy all-important**
 - ★ detailed ckt level simulation, best models
- ★ Takes **months** for a cell library
 - ★ Intel, IBM, AMD, ...

**Finding setup/hold times is
important but expensive**

Setup and Hold Times



Clock-to-Q delay



Is There Only ONE Setup and Hold Time?

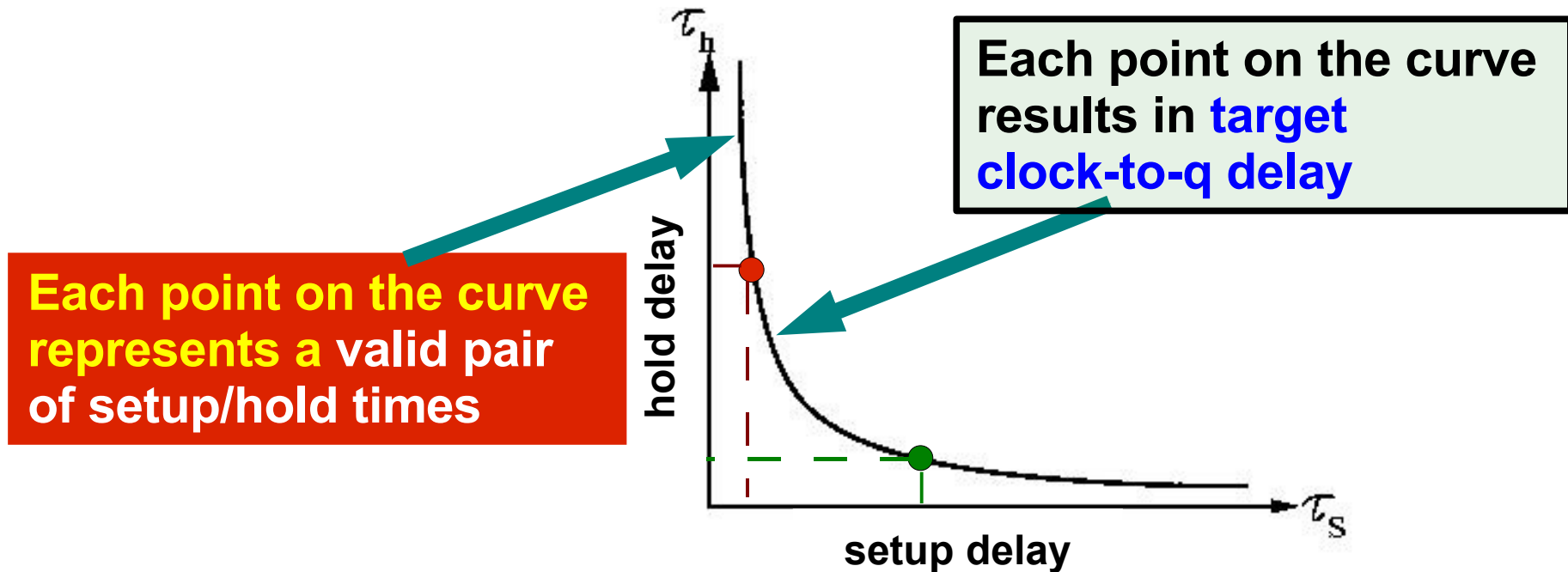
- Assumption made today for STA:
 - ★ setup/hold times unique

Assumption NOT TRUE!

There can be **many pairs of setup/hold times** for a latch/register

Setup/Hold Time Tradeoff Curves

- E. Salman et al 2006 (Ref [1] in paper)

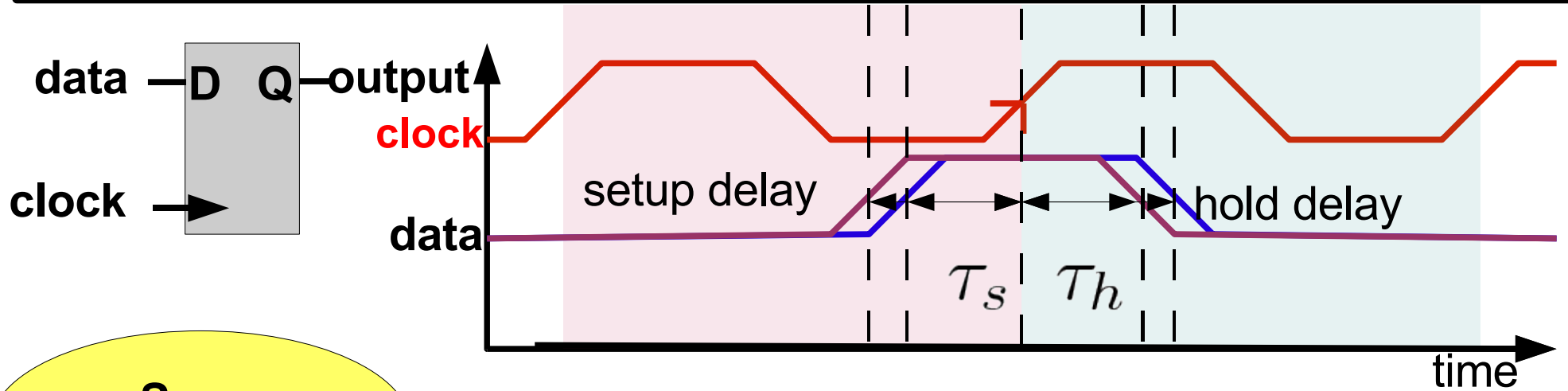


Setup/Hold Time Trade-off Curve

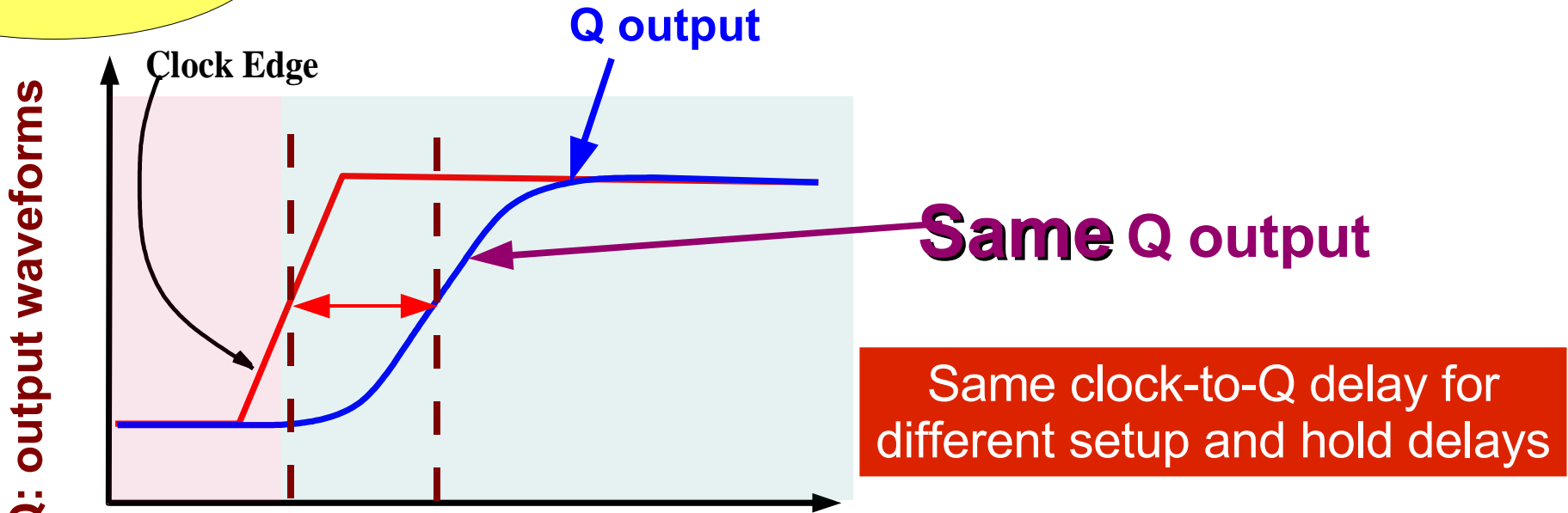
Impact

Reducing pessimism in timing analysis

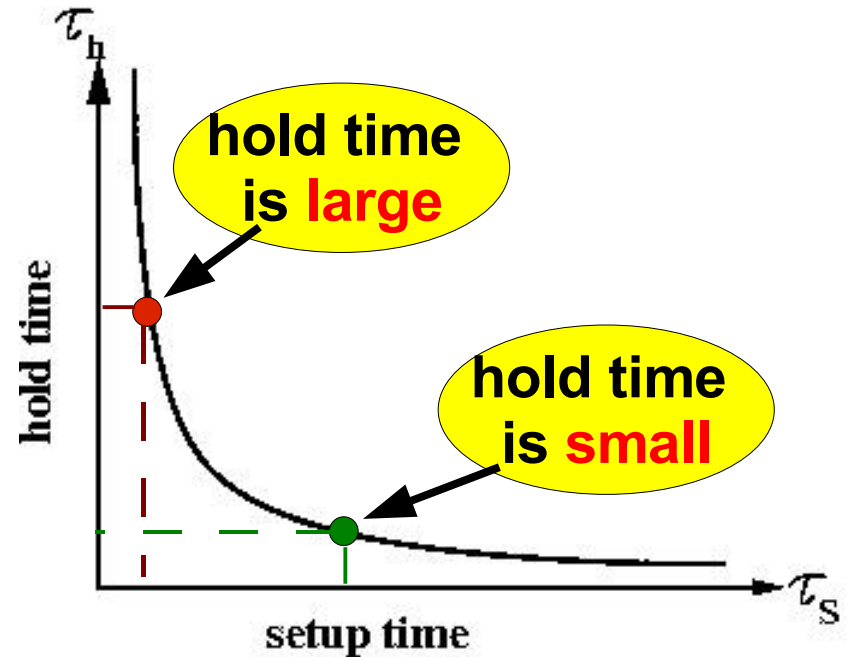
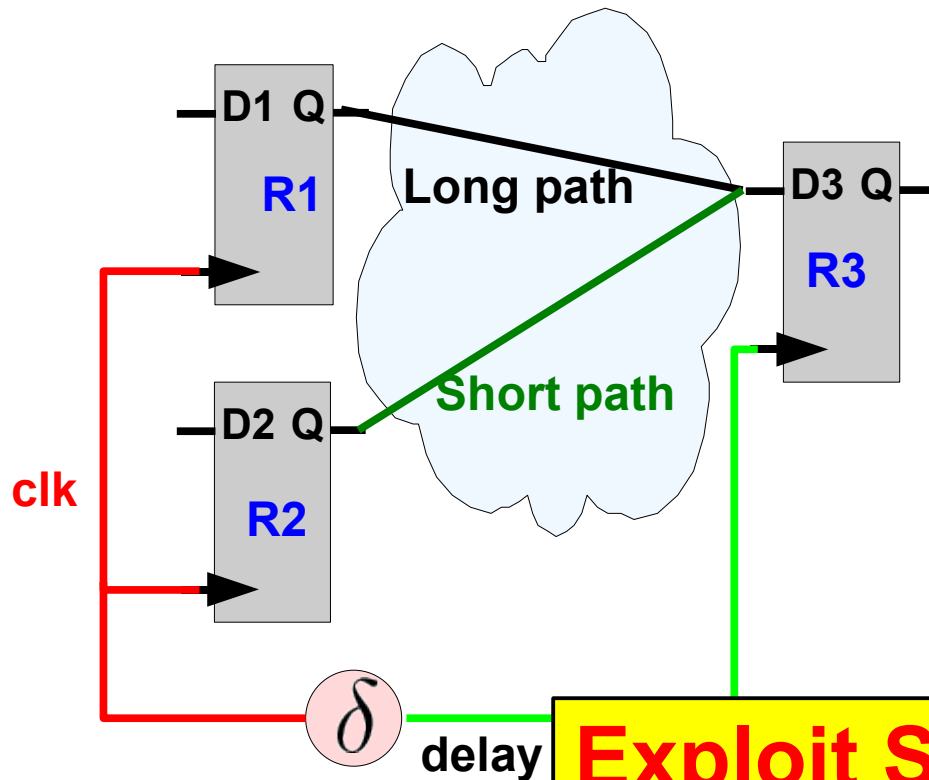
Interdependent Setup and Hold Times



Same Clock-to-Q delay



How to Exploit Setup/Hold Interdependence in Timing Analysis?



Exploit Setup/Hold Time Trade-off

hold violation is removed

at the expense of larger setup time

may not be critical

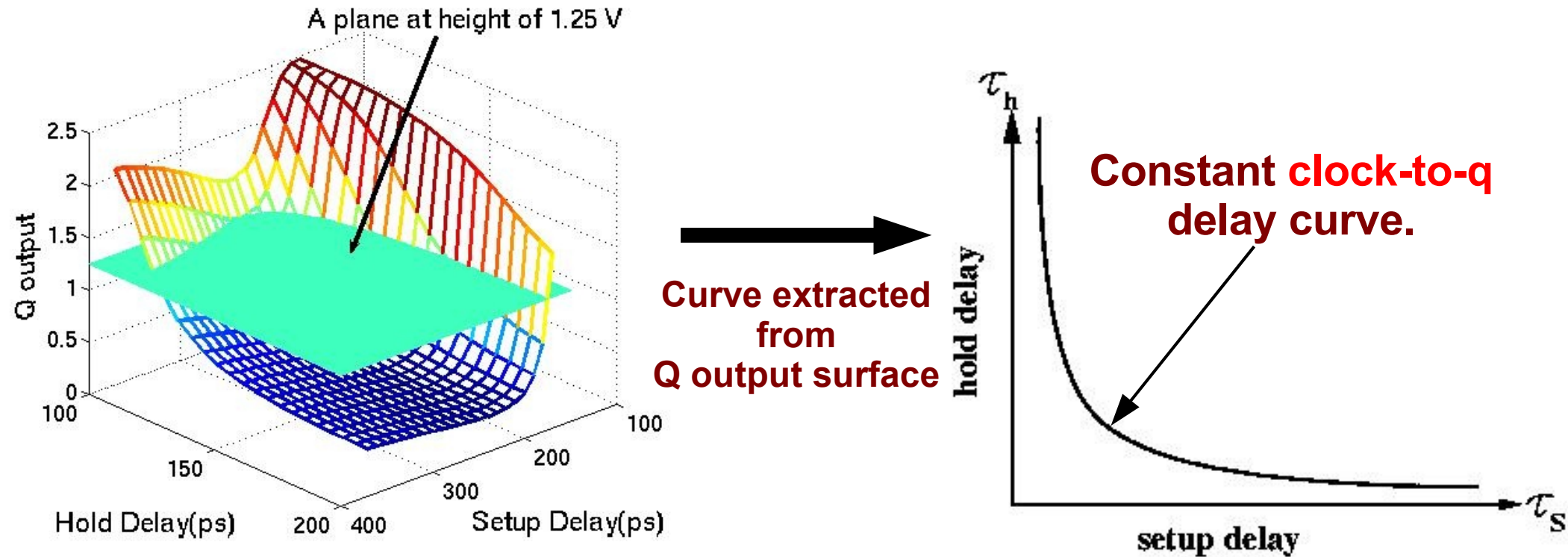
$$\text{hold-time}_{R3} + \delta < \text{clk-to-Q-delay}_{R2} + \text{short-path-delay}$$

Finding Tradeoff Curve is Very Important!

■ Therefore:

- ◆ Finding **setup/hold tradeoff curve is very valuable**
- ◆ **But:**
 - ◆ **Very computationally expensive**

Why Expensive?



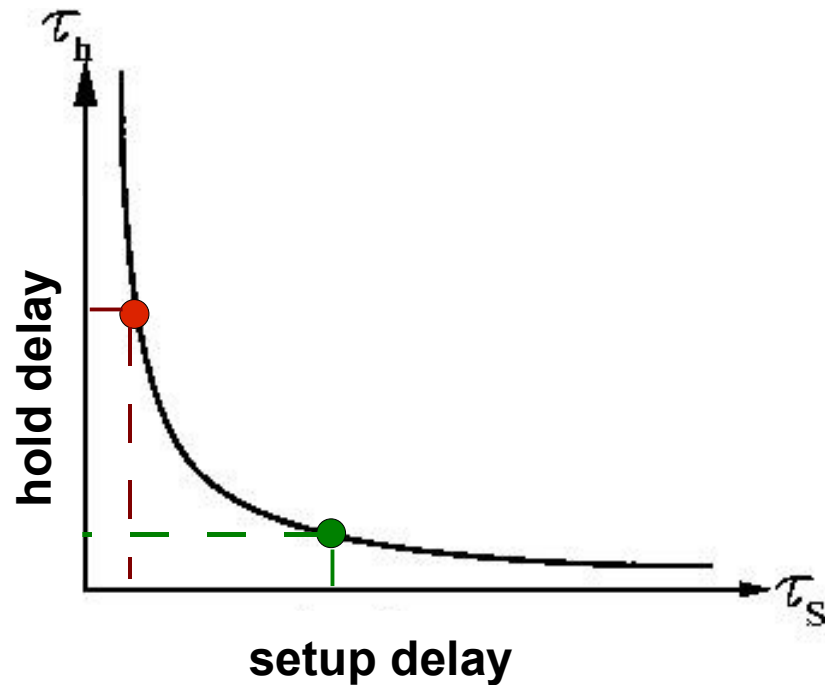
Q value vs setup and hold delays

- ◆ **Problem: finding the full Q surface**
 - ◆ Large number of transient simulations
 - ◆ i.e., infeasible in practice

Our Contribution: Find the Curve **Quickly**

- ◆ **Contribution of this work**
 - ◆ **New setup/hold trade-off curve finding technique**
 - ◆ **much faster than prior brute-force technique**
- ◆ **Key idea: trace the curve “directly”**
 - ◆ **avoid looking at points far from curve**

Our Formulation of the Problem



$$h(\tau_s, \tau_h) = 0$$

- A **scalar** equation with **two** unknowns (setup & hold time)
 - One equation, two unknowns \Rightarrow many solutions (**the curve**)
- Solve numerically using Newton-Raphson method
 - **Rapid convergence**

Contribution: Problem Formulation

Q output waveform

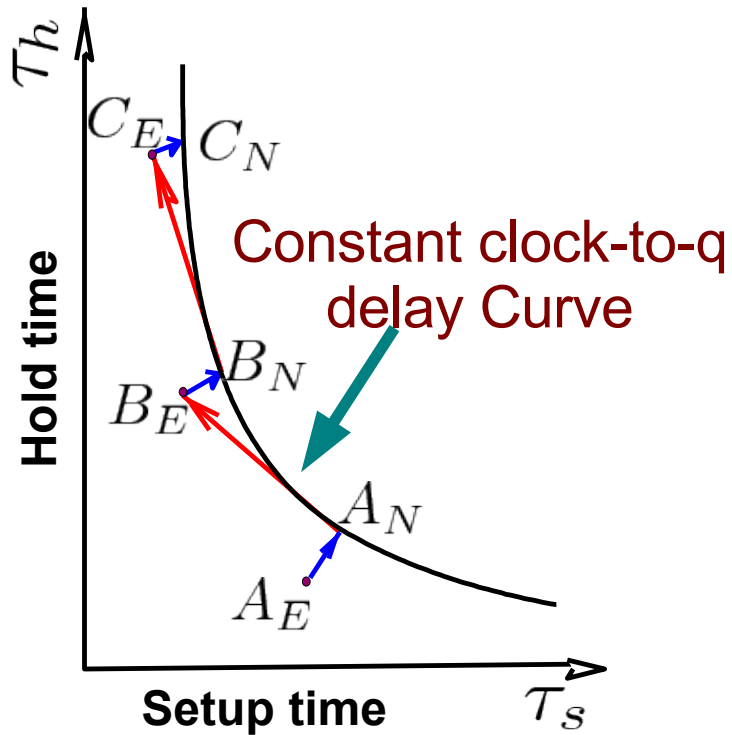
$$Q_{t_f}(\tau_s, \tau_h) = r$$

$$h(\tau_s, \tau_h) \equiv Q_{t_f}(\tau_s, \tau_h) - r = 0$$

- Evaluation of $h(\tau_s, \tau_h)$ is a **transient simulation**
- Solution of **ONE** point
 - ▶ special type of **Newton-Raphson (NR)** method
 - ◆ suitable for underdetermined equations
 - ◆ Moore-Penrose Pseudo Inverse NR (MPPI-NR)
- Finding the entire curve
 - ▶ **Euler-Newton** curve tracing method
 - ▶ Uses MPPI-NR for each point on curve

Intuition Behind Euler-Newton Method

Start with initial guess: $A_E = (\tau_{s0}, \tau_{h0})$



Newton Step + Euler Step

Corrector step
Run Newton-Raphson

Found a point on the curve

C_N

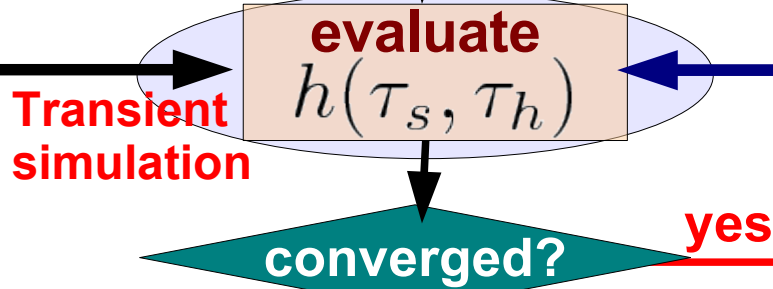
Predictor step
Compute Euler step

Predict a new point along the
tangent of the curve

C_E

Solving $h(\tau_s, \tau_h) = 0$ by Euler-Newton

Start with initial guess (τ_{s0}, τ_{h0})



evaluate **No**

$$H(\vec{\tau}) = \begin{bmatrix} \frac{dh}{d\tau_s} & \frac{dh}{d\tau_h} \end{bmatrix}$$

Moore-Penrose pseudo inverse

$$H(\vec{\tau})^+ = H(\vec{\tau})^t (H(\vec{\tau})H(\vec{\tau})^t)^{-1}$$

update

$$\begin{bmatrix} \tau_s \\ \tau_h \end{bmatrix} = \begin{bmatrix} \tau_s \\ \tau_h \end{bmatrix} + h(\dots)H(\vec{\tau})^+$$

Found a point on the curve

Compute unit tangent vector

$$T(H(\vec{\tau})) = \begin{pmatrix} \frac{-dh}{d\tau_h} \\ \frac{dh}{d\tau_s} \end{pmatrix} \frac{1}{length}$$

Predict a new point along tangent

$$\begin{bmatrix} \tau_{s0} \\ \tau_{h0} \end{bmatrix} = \begin{bmatrix} \tau_s \\ \tau_h \end{bmatrix} + \alpha \cdot T(H(\vec{\tau}))$$

Connections with “RF” Simulation

■ New Algorithm:

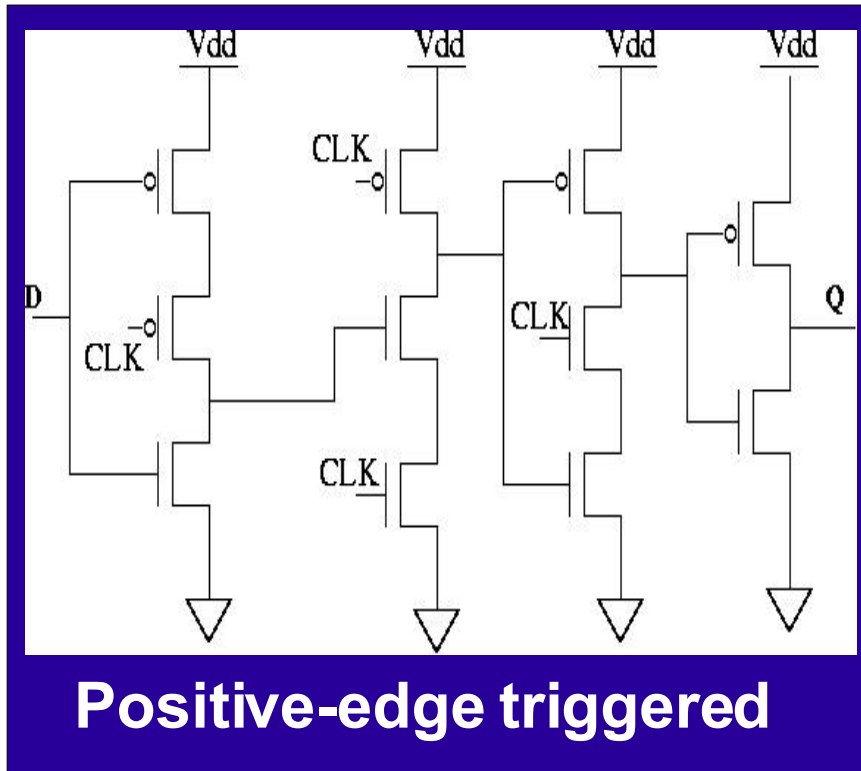
- ▶ very similar to shooting method
- ▶ used in “RF” simulation

- ▶ Implementation easy in RF simulators
 - ◆ Eg, **SPECTRE-RF (Cadence), MICA (Freescale)**

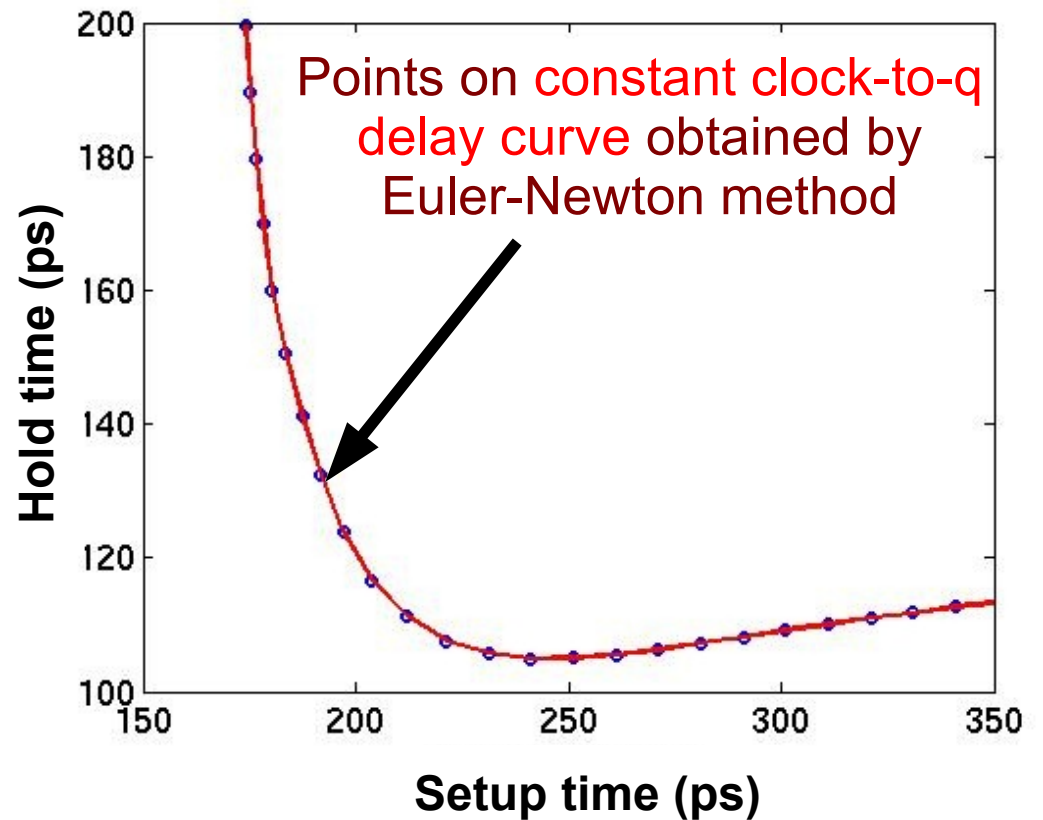
- ▶ “RF” simulation capabilities important for:
 - ◆ **core characterization of digital circuits!**

Validation

Validation on TSPC register



True Single-Phased Clocked register

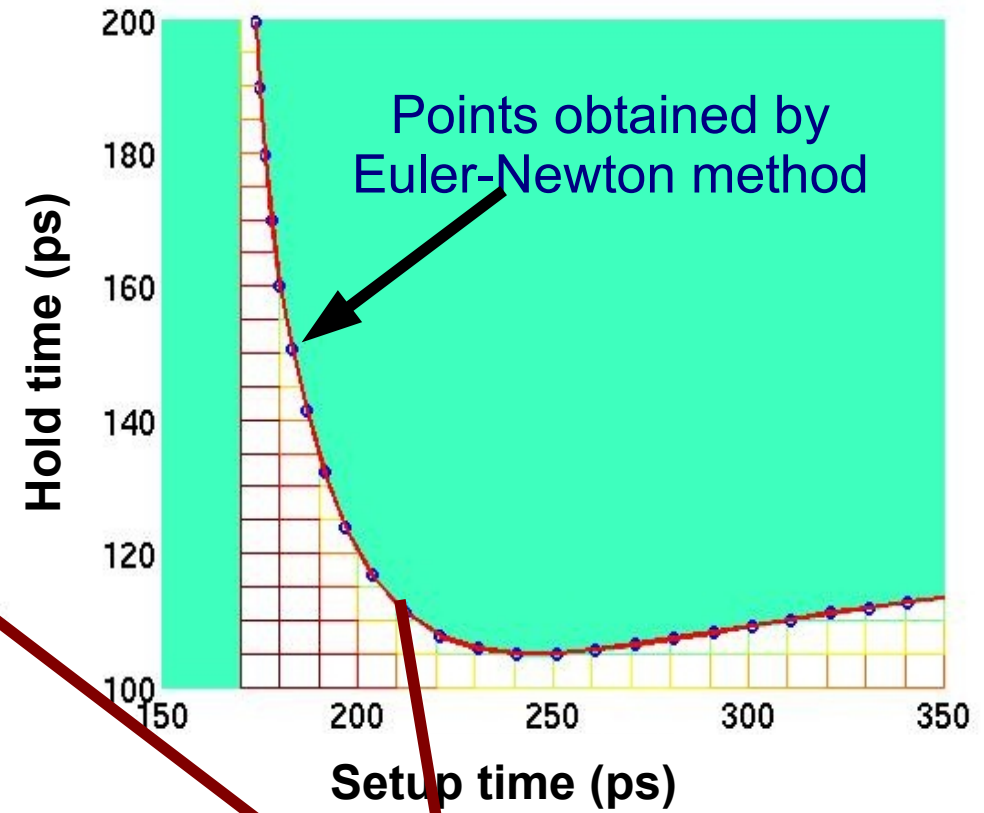
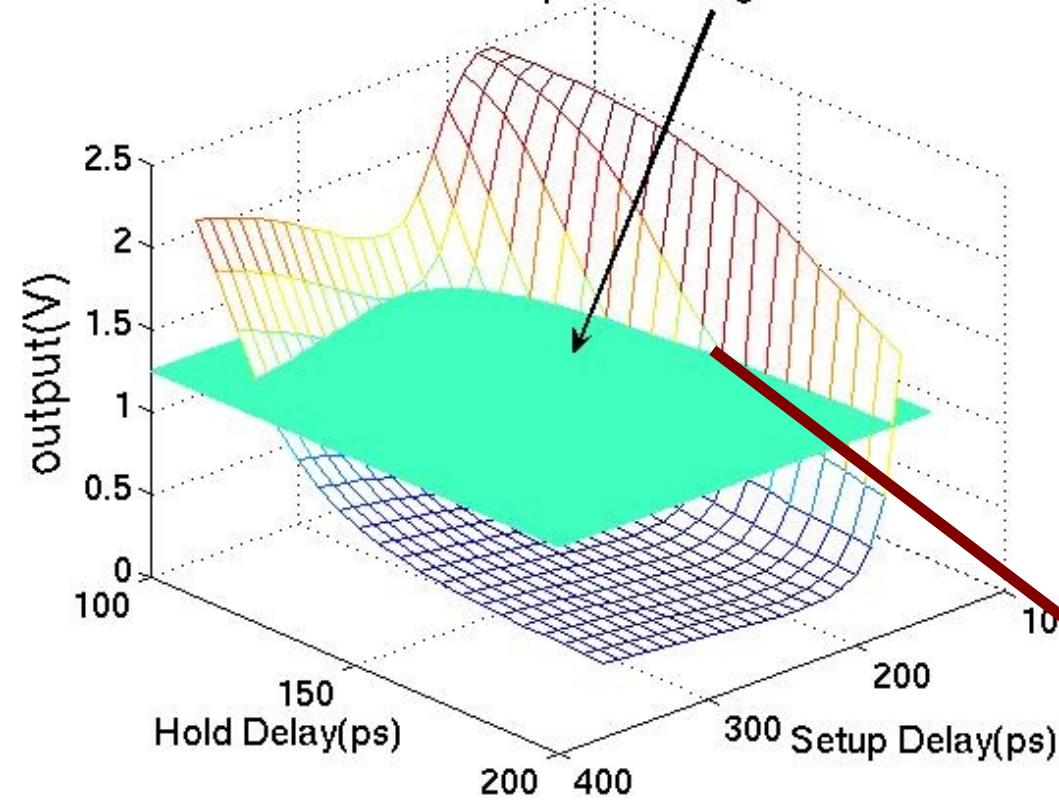


Curve represents the pairs of setup and hold times – each point on curve results in 10% increase in nominal clock-to-Q delay

TSPC register validation

Speedup: ~12.5x (30min vs 6h 40min)

A plane at height of 1.25 V

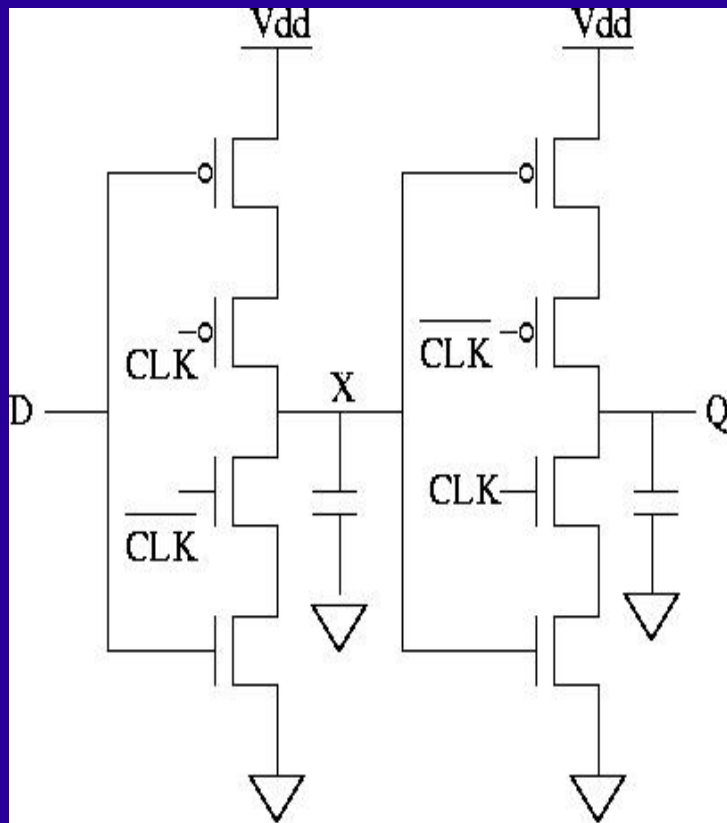


Q output surface as a function of setup and hold delays

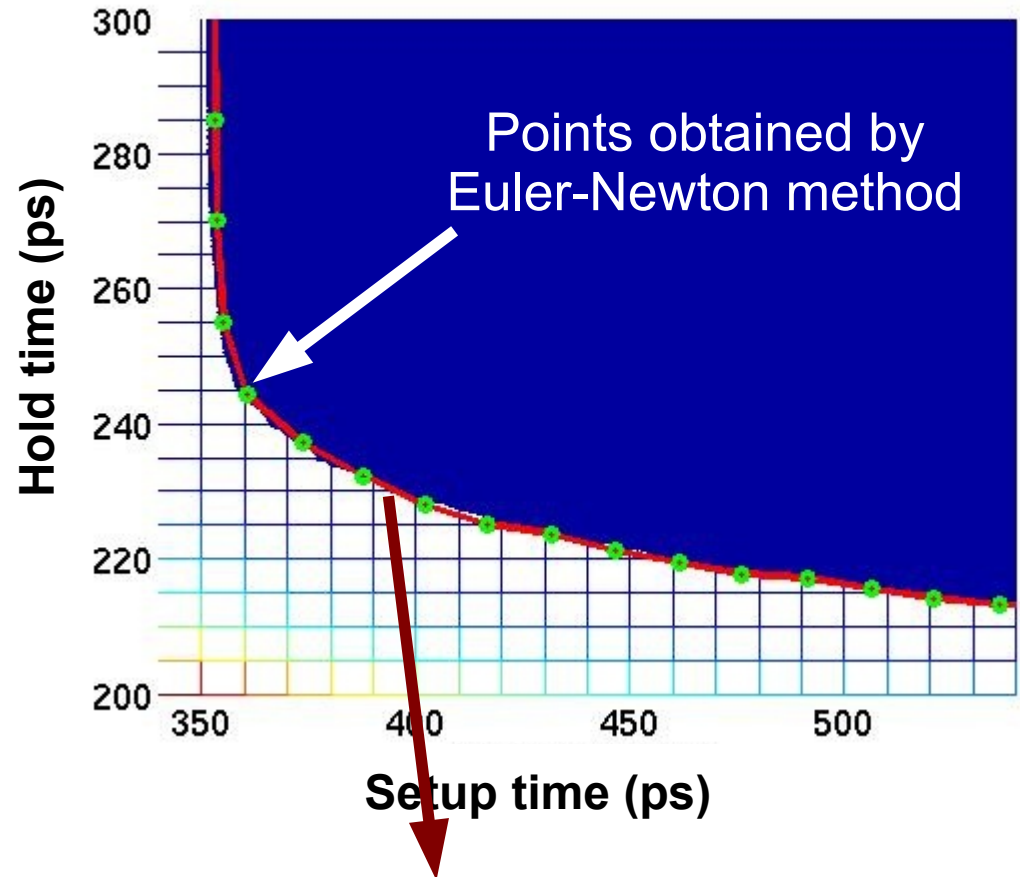
Curve extracted from Q output surface: Brute-force method

C²MOS register: Validation

Speedup: ~10.5x (16min vs 2h 48min)



Positive -edge triggered



Curve extracted from Q output surface: Brute-force method

Summary

- **New technique for fast setup/hold tradeoff curve characterization**
 - ▶ **Adapts ideas from “RF” simulation (shooting)**
- **Importance/Impact:**
 - ▶ **“free” elimination of violations/slack in timing analysis**
 - ▶ **reduces unnecessary optimism or pessimism**
- **Validated on TSPC and C2MOS registers**
 - ▶ **Speedups of an order of magnitude**

Key advance in making setup/hold tradeoff exploitation
PRACTICAL

Acknowledgments

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